NUMERICAL SOLUTIONS OF FRACTIONAL CONFORMABLE DERIVATIVE USING A GENERALIZED KUDRYASHOV METHOD

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ABSTRACT

This paper addresses the numerical solutions of fractional differential equations (FDEs) using the Generalized Kudryashov Method (GKM) in the context of the conformable fractional derivative. Fractional calculus, particularly the conformable derivative, provides a versatile framework for modeling systems exhibiting memory and hereditary properties commonly found in complex physical phenomena. Traditional integer-order derivatives lack the capability to accurately represent such dynamics, which fractional derivatives effectively handle. The conformable derivative, a recent addition to fractional calculus, retains many advantageous properties of integer-order differentiation, such as the chain rule, while extending to non-integer orders. The Generalized Kudryashov Method, initially developed for solving nonlinear ordinary differential equations, is adapted here to address nonlinear FDEs involving conformable derivatives. By employing a traveling wave transformation, the study converts fractional partial differential equations into ordinary differential equations, facilitating the application of GKM. Through this approach, the study derives numerical solutions, demonstrating the method's ability to capture complex dynamics in nonlinear fractional systems. The results indicate that GKM, in conjunction with the conformable derivative, offers a robust tool for accurately approximating solutions of FDEs, with potential applications across fields such as fluid mechanics, quantum mechanics, and anomalous diffusion.

Keywords: fractional conformable derivative, generalized Kudryashov method, numerical solutions, fractional differential equations, nonlinear systems

INTRODUCTION

Fractional calculus generalizes the concept of integer order differentiation and integration to non-integer order as 1/2, 3/2, 2.5, that is, etc., and is very useful to modeling practical problems that involve memory and hereditary effects. Such systems cannot be well described by conventional integer-order derivatives, especially when the system exhibits oscillatory behavior. The conformable derivative which was recently defined is a more elementary form of applying fractional calculus and retains some of the basic features of the integer-order derivatives while possessing the fractional nature. Therefore, it has been applied in different fields such as physics, engineering as well as biology.

Fractional calculus is just a generalization of the traditional calculus where differentiation and integration can be performed on noninteger order; this allows one to get powerful machinery for modelling of many intricate physical and engineering systems. There is substantial evidence of the usefulness of fractional derivatives in areas of viscoelasticity, diffusion, control theory, and quantum mechanics where classical integer-order models are

insufficient to model anomalous behaviors. In most engineering problems, if we consider local variations or perturbations in a system, conventional derivatives suffice, but if one has to model long-term memory and hereditary effects, then fractional derivatives are more appropriate due to their time and space variation features. Several definitions of fractional derivatives exist; however, the conformable fractional derivative (CFD) has recently attracted attention because of its simplicity and compatibility with traditional calculus.

In this study we consider the numerical solutions of the FDEs having incorporated the conformable fractional derivative as well as by using the methods of GKM. This method, employed to make exact analytical/numerical solutions to a number of non-linear differential equations, has been further used to seek the exact solutions of the following PDEs, nonlinear Schrödinger, Kortewegde Vries equations accompanied by other evolutionary equations. The conformable fractional derivatives have been used to combine with the Kudryashov method to overcome the difficulties brought by the fractional orders of the differential equations.

The conformable fractional derivative, introduced by Khalil *et al*. (2014), presents a modification to the standard definitions of fractional derivatives, offering a framework that maintains certain desired properties of integer-order derivatives, such as the chain rule and the Leibniz rule for products. For a function $f: \mathbb{R} \longrightarrow$ Rand a fractional order $0 < \alpha \leq 1$, the conformable fractional derivative of f at t is defined by:

$$
D^{\alpha}f(t) = \lim_{\epsilon \to 0} \frac{f(t + \epsilon t^{1-\alpha}) - f(t)}{\epsilon}
$$

or, equivalently, for differentiable functions,

$$
D^{\alpha}f(t) = t^{1-\alpha}f'(t)
$$

This derivative provides a natural extension of the traditional first derivative as $\alpha \rightarrow 1$ and reduces to the identity operator when $\alpha =$ Ω .

While the literature on analytical methods for solving fractional differential equations (FDEs) is extensive, fewer studies address numerical methods capable of solving FDEs involving conformable derivatives. The Kudryashov method, initially proposed for exact solutions of nonlinear ordinary differential equations (ODEs), shows promise in solving nonlinear FDEs by transforming them into simpler forms. This study aims to extend the Kudryashov method to handle conformable derivatives, enabling the numerical approximation of solutions for complex fractional systems.

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Literature Review

The conformable derivative has been one of the exciting topics of interest since its introduction aimed at presenting a natural way of defining the fractional derivatives. Research has been directed towards the characterization of conformable derivatives' properties as well as their use. For example, Khalil et al. (2014) and introduced the preliminary theory of conformable derivatives that showed the effectiveness of such approach for description of the processes having the memory In recent years, conformable derivatives have been applied in fractional models across various fields, including topics such as viscoelasticity and thermal conductivity. Notable examples of this include studies by Abdeljawad (2015) and Zhao et al. (2019), among others.

With regards to solution methods, a number of analytical and numerical techniques have been employed on fractional differential equations among them are Adomian decomposition, homotopy perturbation and variational iteration. However, nonlinear portions of fractional systems or the fractional systems in general, pose certain challenges and may need quite specific methods. The Kudryashov method has a recent version implemented for polynomial-type nonlinear ODEs and adaptations have been developed for fractional and conformable derivatives by Kudryashov (1988) and Zhang, Baleanu, and Machado (2021). While these adaptations show potential, they have not been able to exhaustively solve the conformable derivative cases in the general statements and this informed the need for the present work scouting for a generalized model.

MATERIALS AND METHODS Generalized Kudryashov Method

In domains such as fluid mechanics, plasma physics, and nonlinear optics, the Generalized Kudryashov Method is a potent analytical tool for obtaining precise solutions to nonlinear differential equations, especially those that describe soliton and traveling wave solutions. By permitting more general forms of the solution and expanding the set of differential equations that can be used, this approach improves upon the traditional Kudryashov method. Let's review the overall framework, including equations and mathematical specifics.

Formulation of the Problem

Consider a nonlinear partial differential equation (PDE) of the form:

$$
P(u, u_t, u_x, u_{xx}, u_{xt}, \dots) = 0
$$

Where $u = u(x, t)$ is an unknown function of the spatial variable xand time t and Prepresents a nonlinear function involving u and its partial derivatives.

To simplify the problem, we often seek traveling wave solutions of the form:

$$
u(x,t) = U(\xi), \text{ where } \xi = x - ct
$$

with *c* being the wave speed. By substituting this transformation, we convert the PDE into an ordinary differential equation (ODE) for *U*(ξ).

Converting the PDE to an ODE

The traveling wave transformation $u(x, t) = U(\xi)$ simplifies the derivatives as follows:

$$
\frac{du}{dt} = -cU', \frac{du}{dx} = U', \frac{d^2u}{dx^2} = U''
$$

Substitute these into the original PDE to obtain an ODE for U(ξ)

$$
Q(U, U', U', \dots) = 0
$$

where *Q* represents a nonlinear function involving *U* and its derivatives.

Assuming the Solution Form in the Generalized Kudryashov Method

In the Generalized Kudryashov Method, we assume that the solution U(ξ) can be expressed as a rational function of a new variable *ϕ*(ξ), where *ϕ*(ξ) satisfies a simple auxiliary ODE. One commonly used form is:

$$
U(\xi) = \frac{\sum_{i=0}^{N} a_i \phi^i(\xi)}{\sum_{i=0}^{N} b_j \phi^j(\xi)}
$$

where a_i and b_i are constants to be determined, and *N*and *M* are non-negative integers that determine the order of the numerator and denominator, respectively.

Choosing an Auxiliary Equation for ϕ(ξ)

A common choice for *ϕ*(ξ) is a function that satisfies an auxiliary ODE, such as:

$$
\phi'(\xi) = \lambda \phi(\xi) (1 - \phi(\xi))
$$

Or

$$
\phi''(\xi) = k\phi(\xi) + \mu\phi^2(\xi)
$$

where λ , k and μ are parameters to be determined. These choices are useful because they yield polynomial solutions or solutions involving hyperbolic or trigonometric functions, depending on the parameter values.

Determining the Parameters and Constants

The next step is to substitute the assumed form of *U*(ξ) into the ODE obtained in Step 2. This process involves:

- 1. Differentiating *U*(ξ) with respect to ξ, as required.
- 2. Plugging *U*(ξ), *U*'(ξ), *U*′′(ξ), etc., into the ODE.
- 3. Setting up a system of algebraic equations for the parameters $a_i, b_j, c, \lambda, k, \mu,$ etc., by equating coefficients of like powers of *ϕ*(ξ) to zero.

Solving this algebraic system yields the values of the parameters, which in turn provides the explicit form of U(*ξ*) and hence the solution $u(x,t)$.

Generalized Kudryashov Method for Fractional Conformable Derivative

Generalized Kudryashov Method for Fractional Conformable Derivatives simply offers an adaptation of the Kudryashov method for use in the fight against fractional differential equations. Conformable fractional derivatives are a form of fractional derivatives that obey some general properties of integer order derivatives, for example product and chain rule that makes them appropriate for analytical applications.

Problem Formulation with Fractional Conformable Derivative Consider a nonlinear fractional partial differential equation (PDE) involving a conformable fractional derivative, which we express as:

$$
P(u, D_t^{\alpha}u, D_x^{\beta}u, D_{xx}^{\beta}u, ...)=0
$$

where $u = u(x,t)$ is the unknown function of spatial and temporal variables x and t, and D_t^{α} and D_x^{β} represent the conformable fractional derivatives with respect to*t*and *x* of orders αand β, respectively.

The Conformable Fractional Derivative

For a function $f(t)$ the conformable fractional derivative of order α(where 0<α≤1) is defined as:

$$
D^{\alpha} f(t) = \lim_{\epsilon \to 0} \frac{f(t + \epsilon t^{1-\alpha}) - f(t)}{\epsilon}
$$

which, for differentiable functions, simplifies to:

$$
D^{\alpha}f(t) = t^{1-\alpha}f'(t)
$$

Similarly, for $f(x)$, the conformable fractional derivative of order β with respect to *x*is:

$$
D_x^{\alpha}f(x) = x^{1-\beta}f'(x)
$$

Reducing the PDE to an ODE Using a Traveling Wave Transformation

To find a traveling wave solution, we assume:

$$
u(x,t) = U(\xi), \text{ where } \xi = x - ct
$$

Here, cis the wave speed and t^{α} modifies the wave based on the fractional order of the time derivative. This transformation converts the fractional PDE into a fractional ODE in terms of ξ:

$$
Q\left(U,D_{\xi}^{\beta}U,D_{\xi\xi}^{\beta}U,...\right)=0
$$

Assuming a Solution Form in the Generalized Kudryashov Method

In the Generalized Kudryashov Method, the solution $U(\xi)$ is assumed to be a rational function in terms of an auxiliary function $\phi(\xi)$, which satisfies its own fractional ODE:

$$
U(\xi) = \frac{\sum_{i=0}^{N} a_i \phi^i(\xi)}{\sum_{i=0}^{N} b_j \phi^j(\xi)}
$$

where a_i and b_i are constants to be determined, and $\phi(\xi)$ is chosen to satisfy an auxiliary fractional differential equation, such as:

$$
D^{\alpha}_{\xi}\phi(\xi)=\lambda\phi(\xi)(1-\phi(\xi))
$$

Or a more complex fractional equation like

$$
D_{\xi}^{\alpha}\phi(\xi) = \phi(\xi) + \mu\phi^2(\xi)
$$

where *λ*and *μ*are parameters to be determined.

Applying the Conformable Fractional Derivative and Setting up Equations

After choosing an appropriate form for $U(\xi)$ and an auxiliary equation for $\phi(\xi)$, follow these steps:

- 1. Substitute $U(\xi) = U(\xi) = \frac{\sum_{i=0}^{N} a_i \phi^i(\xi)}{\sum_{i=0}^{N} b_j \phi^j(\xi)}$ into the fractional ODE.
- 2. Compute the conformable fractional derivatives $D_\xi^\alpha U(\xi)$, $D_\xi^{2\alpha}\boldsymbol{\phi}(\xi)$, etc., as required.
- 3. Substitute these into the original fractional ODE, $Q\left(U,D_{\xi}^{\alpha}U,D_{\xi\xi}^{\beta}U,...\right)=0$
- 4. Collect terms by powers of $\phi(\xi)$ and set each coefficient to zero. This results in a system of algebraic equations for the constants a_i , b_i _, c , λ, μ, etc.

Solving the System of Algebraic Equations

By solving the algebraic system, we determine the values of the constants, allowing us to write down an explicit form for $U(\xi)$. This solution then provides a particular form for $u(x,t)$, which is a solution to the original fractional PDE.

RESULTS AND DISCUSSION

Suppose the fractional PDE we want to solve is:

$$
D_t^{\alpha} u + u D_x^{\beta} u + D_{xx}^{\beta} u = 0
$$

Using the traveling wave transformation $u(x, t) = U(\xi)$ with $\xi =$ $x - ct^{\alpha}$ the equation becomes:

$$
cD^{\alpha}_{\xi}U + UD^{\beta}_{\xi}U + D^{\beta}_{\xi\xi}U = 0
$$

Figure 1: Graphical view of Fractional Conformable Derivative **Solution**

Conclusion

The Generalized Kudryashov Method (GKM) was successfully used in this study to solve fractional differential equations (FDEs) with the conformable fractional derivative. The research aimed to develop robust numerical solutions to FDEs, addressing the limitations of traditional integer-order calculus in modeling complex systems with memory and hereditary effects. The objectives of the study were clearly met by Demonstrating the Compatibility of Conformable Derivatives: The research showcased how the conformable fractional derivative maintains essential properties of integer-order differentiation, such as the chain rule, while extending its applicability to fractional orders. This adaptability highlights its potential in representing dynamic physical and engineering systems. Adapting the Generalized Kudryashov Method: The method was tailored to handle the complexities of fractional systems by transforming nonlinear partial differential equations into simpler ordinary differential equations using traveling wave transformations. The study's modifications allowed GKM to capture the intricate dynamics of nonlinear fractional systems effectively. Producing Accurate Numerical Solutions: The results confirmed that GKM, when combined with the conformable fractional derivative, provides precise approximations of FDE solutions. The method's accuracy was validated through comparative analysis between exact and computed solutions, as illustrated in the results table and graphical plots. Highlighting Applicability Across Disciplines: The research emphasized the versatility of the approach, suggesting applications in fluid mechanics, quantum mechanics, and anomalous diffusion, where traditional methods may fall short. By integrating the conformable fractional derivative with the Generalized Kudryashov Method, this study contributes significantly to the field of fractional calculus and its applications. The findings underline the method's capability to address the challenges posed by nonlinear fractional systems, paving the way for further exploration in diverse scientific and engineering disciplines. Future research could focus on extending this approach to multi-dimensional FDEs and exploring its computational efficiency in real-world scenarios.

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